

Pole placement problem

Consider a reachable system as

$$\dot{x} = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & \dots & 1 \\ -a_n & \dots & \dots & \dots & -a_1 \end{bmatrix} x + \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix} u, \quad x \in \mathbb{R}^n \quad (*)$$

$$P = \begin{bmatrix} 0 & \dots & 1 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 0 \\ 1 & 0 & \dots & 0 \end{bmatrix}$$

Characteristic polynomial of A is

$$\chi_A(s) = \det(sI - A) = s^n + a_1 s^{n-1} + \dots + a_n$$

Let $u = kx = (k_1 \dots k_n)x \Rightarrow$

$$A + bk = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & \dots & 1 \\ -a_n + k_1 & \dots & \dots & \dots & -a_1 + k_n \end{bmatrix}$$

$$\Rightarrow \det(sI - (A + bk)) = s^n + (a_1 - k_n)s^{n-1} + \dots + a_n - k_1$$

for any desired $q(s) = s^n + \gamma_1 s^{n-1} + \dots + \gamma_n$

$$\Rightarrow k_n = a_1 - \gamma_1, \dots, k_1 = a_n - \gamma_n$$

thus, the pole placement problem is solved!

Now for any reachable system

$$\dot{x} = Ax + bu \quad x \in \mathbb{R}^n, u \in \mathbb{R}$$

$$y = cx$$

Pole placement is solvable if $\exists \tilde{x} = Tx$

$$\text{s.t. } \tilde{A} = TAT^{-1}, \tilde{b} = Tb$$

has the forms in (*).

i.e. $\tilde{A} = \begin{bmatrix} 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & 1 \\ -a_n & \dots & \dots & -a_1 \end{bmatrix}, \tilde{b} = \begin{bmatrix} 0 \\ \vdots \\ b \\ 1 \end{bmatrix}$

$$\tilde{c} = [1 \ 0 \ \dots \ 0]$$

$$\Rightarrow \tilde{\Omega} = \begin{bmatrix} \tilde{c} \\ \vdots \\ \tilde{c}A^{n-1} \end{bmatrix} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & 1 \end{bmatrix} = I_{n \times n}$$

question: \exists such a C and T?

If C and T exist, $\Rightarrow \tilde{A} = TAT^{-1}, \tilde{b} = Tb, c = \tilde{c}T$

$$A = T^{-1}\tilde{A}T$$

$$\Rightarrow \Omega = \begin{bmatrix} c \\ cA \\ \vdots \\ cA^{n-1} \end{bmatrix} = \tilde{\Omega}T$$

$$\tilde{P} = [\tilde{b} \ \dots \ \tilde{A}^{n-1}\tilde{b}] = TP$$

$$\Rightarrow T = \Omega = \begin{bmatrix} c \\ cA \\ \vdots \\ cA^{n-1} \end{bmatrix}$$

$$\begin{bmatrix} c \\ cA \\ \vdots \\ cA^{n-1} \end{bmatrix} [b \ \dots \ A^{n-1}b] = \tilde{P} = \begin{bmatrix} 0 & \dots & 0 & 1 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & 1 \\ 1 & \dots & \dots & 0 \end{bmatrix}$$

$$\Rightarrow c[b \ \dots \ A^{n-1}b] = cP = [0 \ \dots \ 0 \ 1]$$

$$\Rightarrow c = [0 \ \dots \ 0 \ 1] P^{-1}$$

$$\Rightarrow \begin{bmatrix} c \\ cA \\ \vdots \\ cA^{n-1} \end{bmatrix} b = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix} \therefore T^{-1}b = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}$$

We assume $\sum_{i=1}^n d_i CA^{i-1} = 0$ for some d_1, \dots, d_n

$$\text{i.e. } (\alpha_1 C + \alpha_2 CA + \dots + \alpha_n CA^{n-1})b = 0$$

$$\Rightarrow \alpha_n CA^{n-1}b = \alpha_n = 0 \Rightarrow \alpha_n = 0.$$

$$(\alpha_1 C + \dots + \alpha_{n-1} CA^{n-2})b = 0 \Rightarrow \alpha_{n-1} = 0$$

!

$$\alpha_1 = 0$$

$\Rightarrow T = \Omega$ is nonsingular!

$$\Rightarrow \tilde{X} = T x = \begin{bmatrix} C \\ \vdots \\ CA^{n-1} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$$\Rightarrow \tilde{X}_i = CA^{i-1} x, \quad i=1, \dots, n$$

$$\Rightarrow \boxed{\begin{aligned} \dot{\tilde{X}}_i &= CA^{i-1} \dot{x} \\ &= CA^i x + CA^{i-1} b u \end{aligned}}$$

$$\Rightarrow \dot{\tilde{X}}_i = \tilde{X}_{i+1} \quad i=1, \dots, n-1$$

$$\begin{aligned} \dot{\tilde{X}}_n &= CA^{n-1} \dot{x} \\ &= CA^n x + CA^{n-1} b u \\ &= CA^n x + u \end{aligned}$$

By Cayley-Hamilton theorem, $\chi_A(A) = 0$.

$$\Rightarrow A^n + a_1 A^{n-1} + \dots + a_n I = 0.$$

$$\Rightarrow \dot{\tilde{X}}_n = C(-a_1 A^{n-1} x - \dots - a_n x) + u$$

$$= -a_n \tilde{x}_n - \dots - a_1 \tilde{x}_1 + u$$

$$\dot{\tilde{x}} = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ \vdots & & & & \\ 0 & & & & 1 \\ -a_n & & & & -a_1 \end{bmatrix} \tilde{x} + \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix} u$$

$$z = [1 \ 0 \ \dots \ 0]$$

Example: $\dot{x} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} x + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$, $\dot{x}_1 = x_2$
 $\dot{x}_2 = u$

reachable.

I want $q(s) = (s+r)(s+2r) = s^2 + 3rs + 2r^2$

$$\Rightarrow k_1 = -2r^2, \quad k_2 = -3r$$

$$\therefore e \quad u = -2r^2 x_1 - 3r x_2$$

$$\Rightarrow A + bk = \begin{bmatrix} 0 & 1 \\ -2r^2 & -3r \end{bmatrix} \quad r > 0$$

$$s_1 = -r, \quad s_2 = -2r$$

$$\Rightarrow \dot{x} = \begin{bmatrix} 0 & 1 \\ -2r^2 & -3r \end{bmatrix} x$$

$$e^{(A+bk)t} = \begin{bmatrix} 2e^{-rt} - e^{-2rt} & \frac{1}{r}(e^{-rt} - e^{-2rt}) \\ 2r(e^{-rt} - e^{-2rt}) & -e^{-rt} + 2e^{-2rt} \end{bmatrix}$$

if $x_1(0) = 1, \quad x_2(0) = 0$.

$$x_2(t) = 2r(e^{-rt} - e^{-2rt})$$

$$x_2(t^*) = \frac{r}{2}$$



We show now being reachable is sufficient for pole placement for multiple input system as well.

Consider

$$\dot{x} = Ax + Bu, \quad x \in \mathbb{R}^n, \quad u \in \mathbb{R}^m$$

Assume (A, B) is reachable.

Question: can we find $u = u_0 v$, $v \in \mathbb{R}$
 $u_0 \in \mathbb{R}^m$

$$\Rightarrow \quad \begin{aligned} \dot{x} &= Ax + (Bu_0)v \\ &:= Ax + bv \end{aligned}$$

s.t. (A, b) is also reachable. ?

Yes, we can do this if A is cyclic

Def: A is cyclic if each distinct eigenvalue of A has only one Jordan block.

Example: $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$

Claim: if (A, B) is reachable, then

for all most all $u = Kx$, $A+BK$
is cyclic.

$$\Rightarrow u = Kx + u_0 v$$

$$\Rightarrow \dot{x} = (A+BK)x + B u_0 v$$

$\Rightarrow (A+BK, B u_0)$ is reachable

then we can solve the problem
by designing $v = kx$

$$\Rightarrow u = (K + u_0 k)x$$

Now we show being reachable is also
necessary for pole placement problem.

We assume $\exists u = Kx$ s.t. $A+BK$
^{real and} has n distinct eigenvalues $\lambda_1, \dots, \lambda_n$, s.t.
 $\lambda_i > \|A\|$, $i=1, \dots, n$.

Let z_i be the eigenvector for λ_i , i.e.

$$(A+BK)z_i = \lambda_i z_i, \quad i=1, \dots, n$$

$[z_1 \dots z_n]$ is nonsingular.

We show now $z_i \in \text{Im } P$, $i=1, \dots, n$

$$\Rightarrow (A - \lambda_i I)z_i = -BKz_i$$

$$\Rightarrow (I - \frac{A}{\lambda_i}) z_i = BK \frac{z_i}{\lambda_i}$$

$$\Rightarrow z_i = (I - \frac{A}{\lambda_i})^{-1} BK \frac{z_i}{\lambda_i}$$

$$\frac{1}{1-x}$$

$$= (I + \frac{A}{\lambda_i} + \frac{A^2}{\lambda_i^2} + \dots) BK \frac{z_i}{\lambda_i}$$

$$= BK \frac{z_i}{\lambda_i} + ABK \frac{z_i}{\lambda_i^2} + \dots$$

$$\Rightarrow z_i \in \text{Im}(B, AB, \dots, A^H B, \dots)$$

$$= \text{Im}[B \dots, A^H B] = \text{Im } P, \quad i=1, \dots, n.$$

$$\Rightarrow \text{Im } P = \mathbb{R}^n \Rightarrow \text{reachable!}$$